

Notice of Allowability	Application No.	pplication No. Applicant(s)	
	10/511,128	TAKENAKA ET AL.	
	Examiner	Art Unit	
	Rita Leykin	2837	
The MAILING DATE of this communication apperature All claims being allowable, PROSECUTION ON THE MERITS IS herewith (or previously mailed), a Notice of Allowance (PTOL-85) NOTICE OF ALLOWABILITY IS NOT A GRANT OF PATENT RIOF of the Office or upon petition by the applicant. See 37 CFR 1.313	(OR REMAINS) CLOSED i or other appropriate comm IGHTS. This application is	n this application. If not included unication will be mailed in due course. THIS	ve
1. This communication is responsive to			
2. X The allowed claim(s) is/are <u>1-7</u> .			
3. \boxtimes The drawings filed on <u>13 October 2004</u> are accepted by the	e Examiner.		
 4. Acknowledgment is made of a claim for foreign priority ur a) All b) Some* c) None of the: 1. Certified copies of the priority documents have 2. Certified copies of the priority documents have 3. Copies of the certified copies of the priority documents have International Bureau (PCT Rule 17.2(a)). * Certified copies not received: 	been received. been received in Application	on No	
Applicant has THREE MONTHS FROM THE "MAILING DATE" noted below. Failure to timely comply will result in ABANDONN THIS THREE-MONTH PERIOD IS NOT EXTENDABLE.	IENT of this application.		
5. A SUBSTITUTE OATH OR DECLARATION must be subm INFORMAL PATENT APPLICATION (PTO-152) which give			
 6. ☐ CORRECTED DRAWINGS (as "replacement sheets") must (a) ☐ including changes required by the Notice of Draftspers 1) ☐ hereto or 2) ☐ to Paper No./Mail Date (b) ☐ including changes required by the attached Examiner's 	on's Patent Drawing Review	,	
Paper No./Mail Date Identifying indicia such as the application number (see 37 CFR 1 each sheet. Replacement sheet(s) should be labeled as such in the	.84(c)) should be written on t	he drawings in the front (not the back) of R 1.121(d).	
7. DEPOSIT OF and/or INFORMATION about the deposit attached Examiner's comment regarding REQUIREMENT	sit of BIOLOGICAL MAT	ERIAL must be submitted. Note the	
Attachment(s) 1. ☑ Notice of References Cited (PTO-892)	5. ☐ Notice of In	formal Patent Application (PTO-152)	
2. Notice of Draftperson's Patent Drawing Review (PTO-948)	6. 🗌 Interview S	ummary (PTO-413),	
3. ☑ Information Disclosure Statements (PTO-1449 or PTO/SB/0 Paper No./Mail Date 10/13/04	8), 7. Examiner's	Mail Date Amendment/Comment	
 Examiner's Comment Regarding Requirement for Deposit of Biological Material 	8. ⊠ Examiner's 9. ☐ Other	Statement of Reasons for Allowance .	
		Rita Leykin RITA EENKINExaminer PRIMARY EXAMINER	

REASONS FOR ALLOWANCE

1. The following is an examiner's statement of reasons for allowance. The prior art made of record in the attached form PTO-892 considered to be pertinent to the submitted application.

Takenaka et al. US # 5,404,086 disclose a system for controlling locomotion of legged mobile robot and correcting inclinometer's output, wherein a desired walking pattern (gait) is not predetermined. And therefor, the error is estimated and desired walking pattern is corrected in response to the error such that the floor reaction becomes as desired. The floor reaction force is controlled through the angle and desired walking pattern. The error is used to correct output of the inclinometer equipped on robot.

Takenaka et al. US # 5,459,659 disclose an attitude stabilization control system for a legged mobile robot having a trunk and two legs each connected to the trunk such that it walks on the ground. The system generates a desired walking pattern of the robot in such a manner that ground reaction force moment acting on the robot when the robot's leg comes into contact with the ground is at a desired position and is provided with a first model made up of an inverted pendulum and situating dynamics of the robot and a second model simulating the mechanical structure of the robot such that the second model is assumed to walk on the ground in accordance with the desired waking pattern. An inclinatory error of the robot's trunk is detected relative to the second model. A manipulated variable is determined in terms of moment in response to the detected inclinatory error and supplying it to the first model such that the inverted pendulum is

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rotated about its pivot point by an amount corresponding to the manipulated variable. A positional variations corresponding to the trunk is detected resulting from the rotation therefrom, to correct the motion of the second model in response to the detected positional variation. Robot's joints are controlled to follow the motion of the second model, thereby, the robot can move stably over the ground.

However, none of the prior art teaches or suggests the claimed combination of limitations including:

- A drift correction value determining means for determining a drift correction value relative to a detected value of the posture angular velocity detecting means;
- An angular velocity estimated by the slippage free posture angular velocity estimating means;
- Correcting a detected value of the posture angular velocity detecting
 means by using a drift correction value and a posture angular velocity
 estimated by the slippage-free posture angular velocity estimating means
 close to zero.

Any comments considered necessary by applicant must be submitted no later than the payment of the issue fee and, to avoid processing delays, should preferably accompany the issue fee. Such submissions should be clearly labeled "Comments on Statement of Reasons for Allowance."

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Any inquiry concerning this communication or earlier communications from the examiner should be directed to Rita Leykin whose telephone number is (571)272-2066. The examiner can normally be reached on Monday-Friday 8:30-6:00.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, David Martin can be reached on (571)272-2107. The fax phone number for the organization where this application or proceeding is assigned is 703-872-9306.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

Rita Leykin Primary Examiner Art Unit 2837

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